

Supporting Information

Simulation-Guided Design of Solar Steam Generator Arrays for Efficient All-Cold Evaporation under Natural Sunlight

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1. Materials

Commercially available balsa wood was used to fabricate the side fins for three-dimensional (3D) interfacial steam generators (SGs). Polyurethane-based 2D fabrics were prepared through electrospinning, which was used as the photothermal layer. The 3D scaffold was printed based on active foaming polylactic acid (PLA).

2. Characterizations

Contact angles were measured via a contact angle goniometer (JC2000DM, Powereach) by using 4 μL of water droplet as an indicator. The absorption spectra were obtained from a UV–Vis–NIR spectrometer (LAMBDA 1050+, PerkinElmer) with an integrating sphere. The absorbance at each wavelength is defined by $1 - T - R$, where T and R are the corresponding transmittance and reflectance, respectively. The densities, porosity and saturated water contents were measured by using a high-precision density meter (AU-120PF, Quarrz). The morphologies and elemental mapping were characterized by a scanning electron microscope (VEGA3, TESCAN) in combination with energy dispersive X-ray spectrometry. The air velocity was monitored by using a hotline anemometer (AR866A, Sima). The outdoor evaporation experiments were conducted in July at Ocean University of China, Qingdao, China.

3. Numerical simulation

The velocity magnitude, relative humidity distribution, heat transfer and particle distribution were simulated using COMSOL Multiphysics software 6.1 version. A multi-physics module of Turbulent Flow, Moisture Transport, Heat transfer and Particle Tracing for Fluid Flow module was used to evaluate the evaporative dynamics of SG with different numbers of fins as enabled by the different convective flow speeds. The velocity magnitude was simulated by solving the following equations,[1]

$$\text{Re}_w = \frac{\rho |u| \zeta_w}{\mu} = \frac{|u|}{\mu_t} \cdot \frac{\rho \mu_t \zeta_w}{\mu} = u^+ \zeta_w^+, u^+ = f(\zeta_w^+) \quad (\text{S1})$$

$$\nabla G \cdot \nabla G + \sigma_w G (\nabla \cdot \nabla G) = (1 + 2\sigma_w) G^4, \sigma_w = \frac{1}{G} - \frac{\zeta_{ref}}{2} \quad (\text{S2})$$

$$\mu_T = \mu \left(\left(\frac{df}{d\zeta_w^+} \right)^{-1} - 1 \right) \quad (\text{S3})$$

where Re_w is wall Reynolds number, u is the velocity field, ρ is the density of the fluid, μ is the dynamic viscosity, u^+ is dimensionless velocity, ζ_w^+ is dimensionless wall shear stress, σ_w is an argument in the wall function, ζ_{ref} is reference stress, G is the reciprocal wall distance, μ_T is turbulent viscosity.

4. Stability of balsa wood

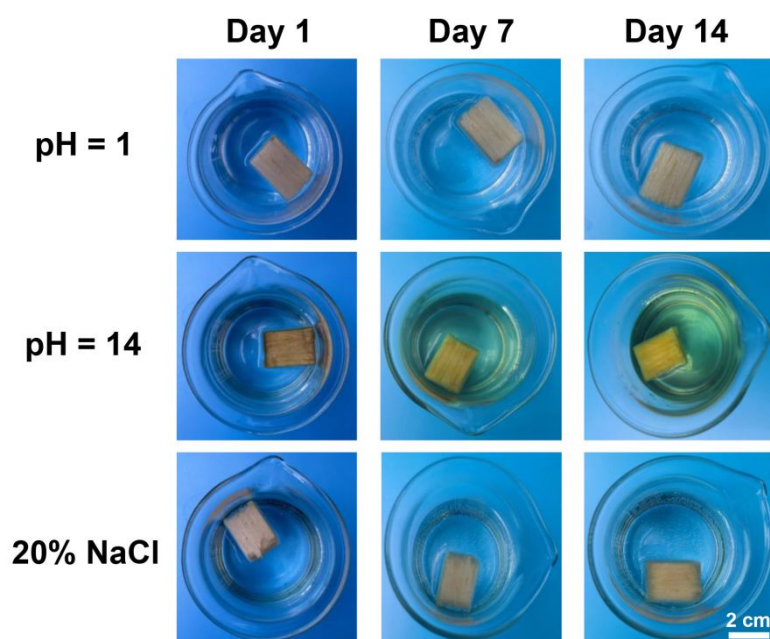


Figure S1. Balsa wood sheets immersed in extreme water conditions.

5. Structural integrity characterization

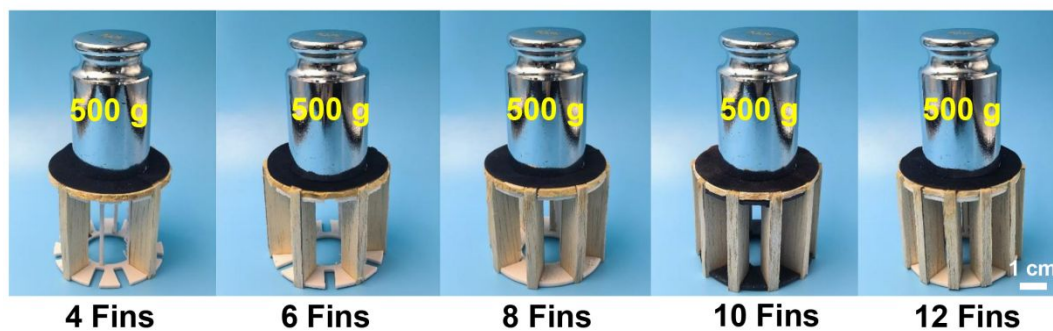


Figure S2. Images of all SGs sustaining a weight of 500 g.

6. Absorption characterization

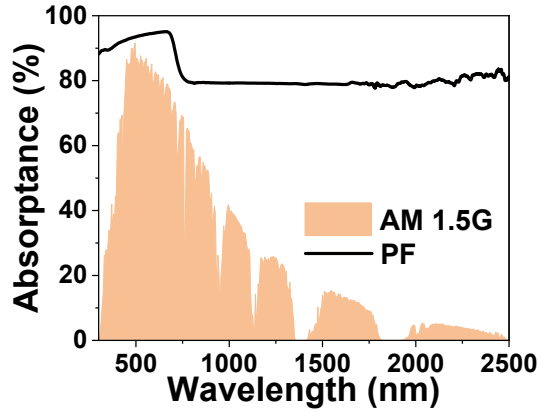


Figure S3. Absorption spectrum of the photothermal fabric.

The transmission and reflection spectra of the aerogel matrix over the whole solar spectrum (250 – 2500 nm) were measured using an UV–Vis–NIR spectrophotometer equipped with an integrating sphere. According to Kirchhoff's law, the absorption spectrum can be obtained through the formula: $A = 1 - R - T$. Therefore, the absorptance (A_t) of the aerogel matrix across the full solar spectrum can be calculated using equation S1,[2]

$$A_t = \frac{\int A \cdot S \cdot d\lambda}{\int S \cdot d\lambda} \times 100\% \quad (\text{S4})$$

where S is solar spectral irradiance ($\text{W m}^{-2} \text{nm}^{-1}$) and λ is wavelength (nm).

7. Fiber diameter distribution

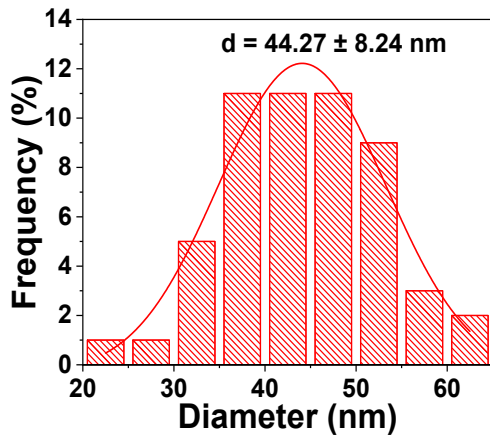


Figure S4. Fiber diameter distribution of the photothermal fabric.

8. Macro photography

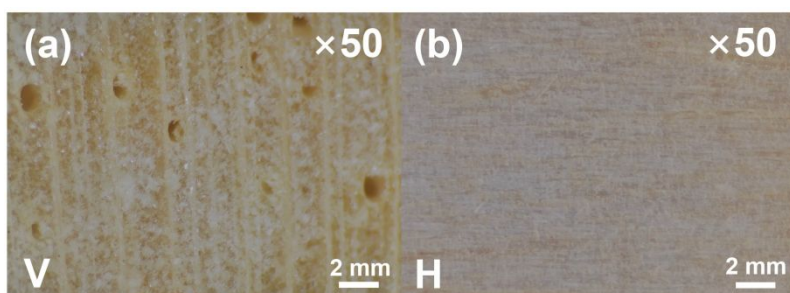


Figure S5. Microscopic photographs of balsa wood along (a) vertical (V) and (b) horizontal (H) growth directions.

9. Contact angle measurements

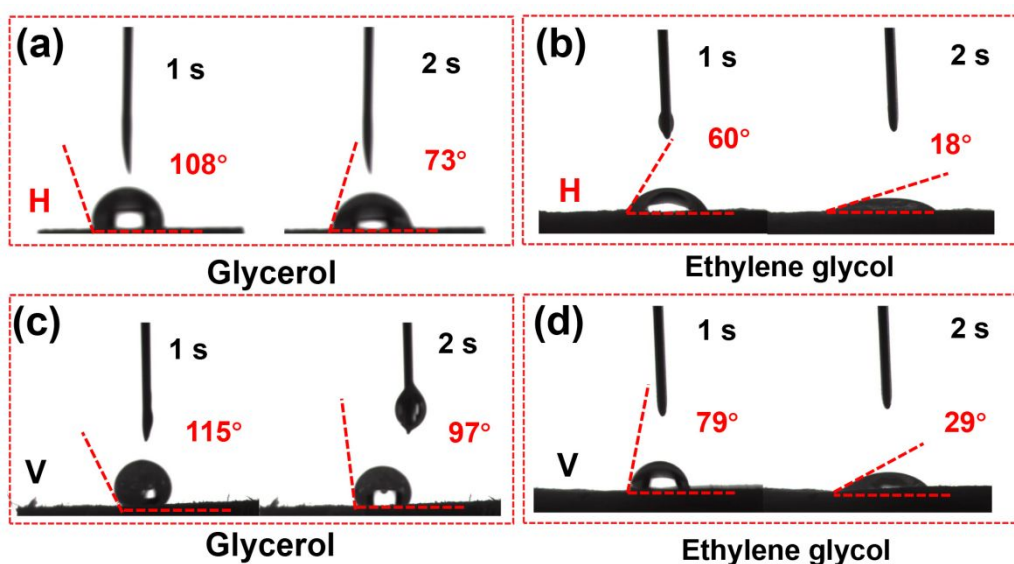


Figure S6. Contact angle (CA) measurements of (a) (b) transverse and (c) (d) longitudinal cross-sections of balsa wood in different organic solvents.

10. Temperature distribution simulation

(a) Physical modeling



(b) Mesh generation

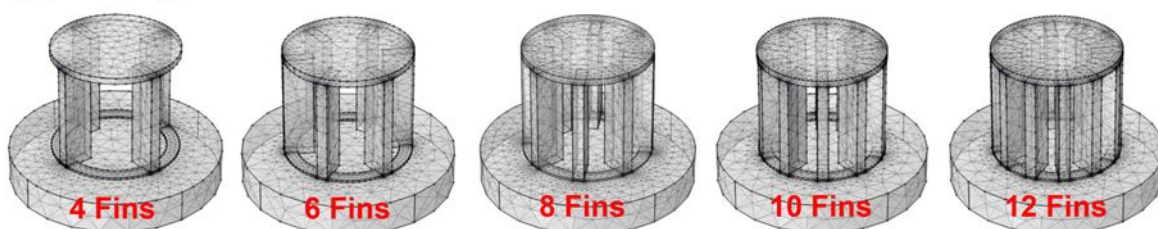


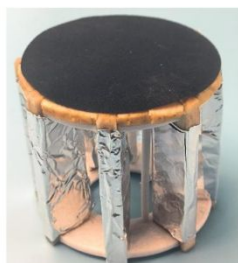
Figure S7. Temperature distribution simulation: (a) physical modeling and (b) mesh generation of five SGs.

11. Evaporation contribution characterization

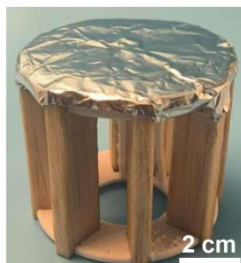
(a) 8-Fin SG



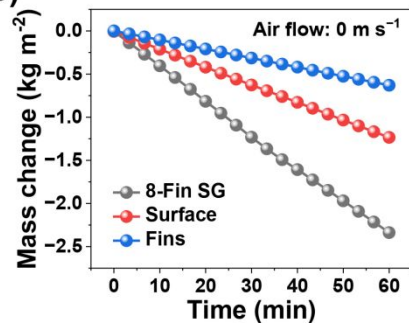
Surface



Fins



(b)



(c)

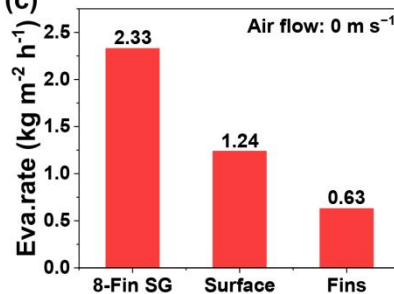


Figure S8. (a) Digital photographs, (b) mass changes of water and (c) evaporation rates of different devices.

12. Energy balance analysis

a) Radiation

The radiation loss was analyzed by Stefan-Boltzmann equation S5,[3]

$$\Phi = \varepsilon A \sigma (T_1^4 - T_2^4) \quad (S5)$$

Φ is heat flux (W), ε denotes emissivity (Supposing the evaporator has a maximum emissivity of 1), A is evaporation surface area, σ represents the Stefan-Boltzmann constant ($\sigma = 5.670373 \times 10^{-8} \text{ W m}^{-2} \text{ K}^{-4}$).[4]

b) Conduction

The heat conduction was analyzed according to the following equation S6,[5]

$$Q = Cm\Delta T \quad (S6)$$

Q denotes the heat energy, C is the specific heat capacity of pure water ($4.2 \text{ J g}^{-1} \text{ K}^{-1}$), m represents the weight of bulk water and ΔT is the reduced temperature of the bulk water after stable steam generation.

c) Convection

The convection was calculated by Newton's law of cooling S7,[6]

$$Q = hA\Delta T \quad (S7)$$

Q is the heat energy, h denotes the convection heat transfer coefficient ($\sim 5 \text{ W m}^{-2} \text{ K}^{-1}$).[7] A represents surface area. ΔT is difference between the ambient temperature around the evaporator and the surface temperature of the evaporator.

d) Reflection

The solar absorption of solar absorber is 91.4%; thus, the reflection loss is $\sim 8.6\%$.

e) Evaporation

The evaporation heat of water is calculated using the following equation S8 and S9,[8]

$$P = m(h_{LV} + Q) \quad (S8)$$

$$Q = C\Delta T \quad (S9)$$

where m is the evaporation rate, h_{LV} is the latent heat of total enthalpy used for the transition of water from liquid to vapor phase, Q is the sensible heat of water, C is the specific heat capacity of pure water ($4.2 \text{ J g}^{-1} \text{ K}^{-1}$), ΔT is the temperature difference between the initial temperature and the evaporation temperature.

Recycled energy = Total output – Total input

Total output = Vapor output + Convection output (top surface to air) + Radiation output (top surface to air)

Total input = Solar input + Environment input

Environment input = Convection input (air to fins) + Radiation input (air to fins) + Conduction input (water to fins)

Table S1. An analysis of energy losses and gains of 8-Fin SG during solar evaporation.

| | |
|------------------------------------|-----------------------|
| Ambient Temperature (K) | 301.15 |
| Top surface area (m ²) | 2.83×10^{-3} |
| Fins area (m ²) | 1.23×10^{-2} |
| Stable top temperature (K) | 310.45 |
| Stable temperature of fins (K) | 299.35 |
| Initial water temperature (K) | 300.85 |
| Stable water temperature (K) | 299.85 |
| Optical absorption coefficient (%) | 91.4 |
| Vapor output (W) | 4.48 |
| Convection output (W) | 0.13 |
| Radiation output (W) | 0.17 |
| Solar input (W) | 2.58 |
| Radiation input (W) | 0.14 |
| Convection input (W) | 0.10 |
| Conduction input (W) | 0.20 |
| Total input (W) | 3.02 |
| Total output (W) | 4.78 |
| Recycle energy (W) | 1.76 |

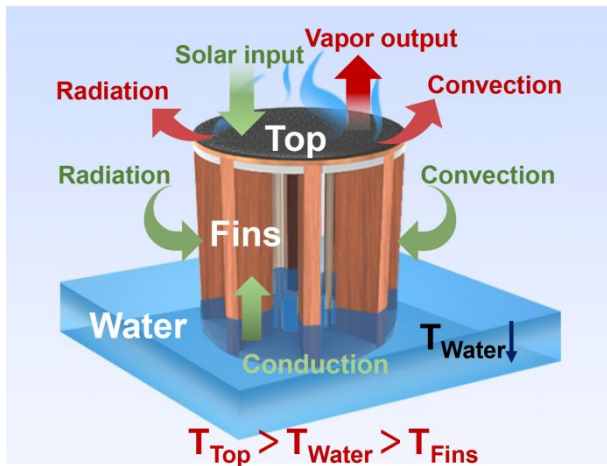


Figure S9. Schematic diagram of heat transfer pathways of 8-Fin SG during indoor solar evaporation.

13. Solar desalination characterization

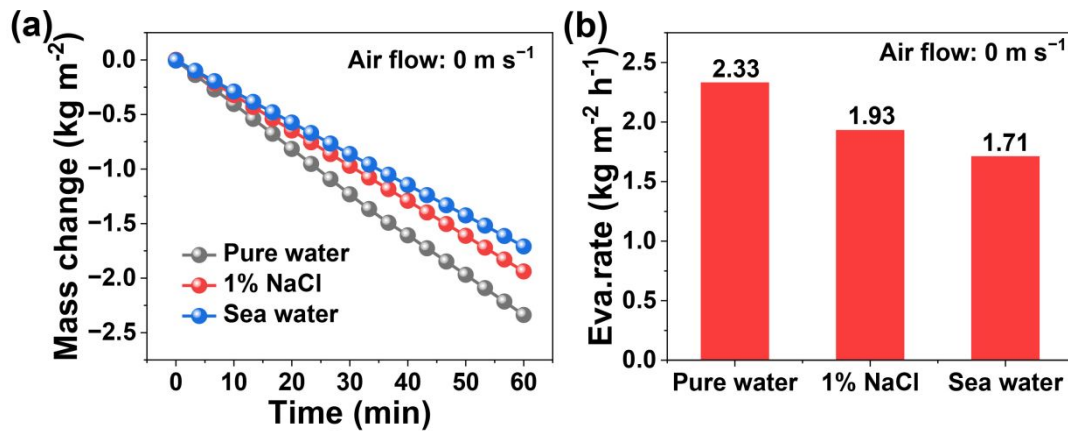


Figure S10. (a) Mass changes and (b) evaporation rate of water of 8-Fin SG in fresh water, 1% NaCl solution and sea water over 1 h under windless and 1 sun conditions.

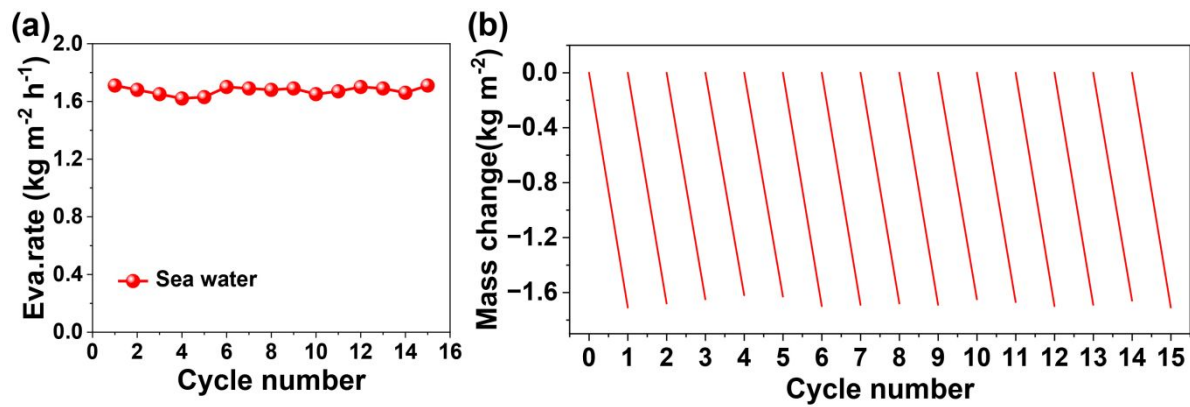


Figure S11. (a) Evaporation rate and (b) mass changes of cyclic solar desalination under windless and 1 sun conditions.

14. Boundary condition of air velocity and RH distribution simulation

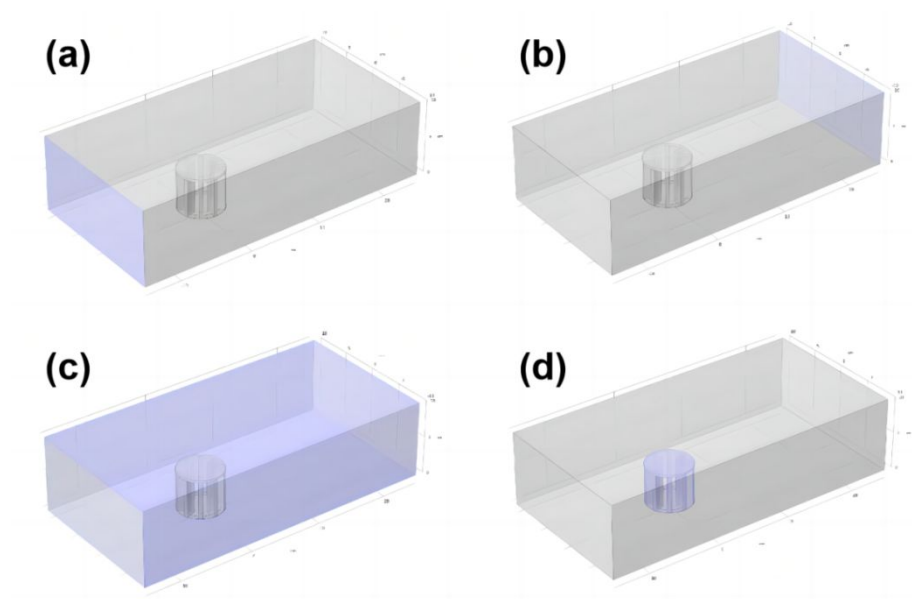
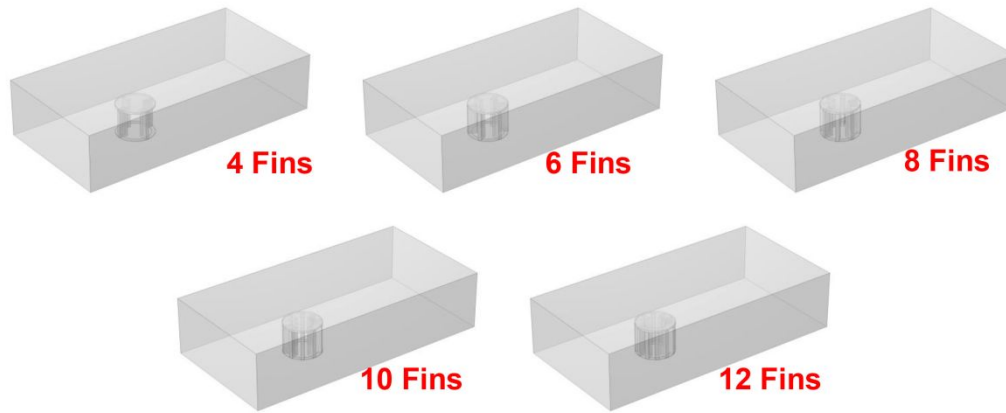


Figure S12. Boundary conditions in air velocity and RH distribution simulation of SG: convective flow (a) inlet and (b) outlet, (c) vapor outlet and (d) evaporation flux of SG.

15. Physical modeling and mesh generation of SGs

(a) Physical modeling



(b) Mesh generation

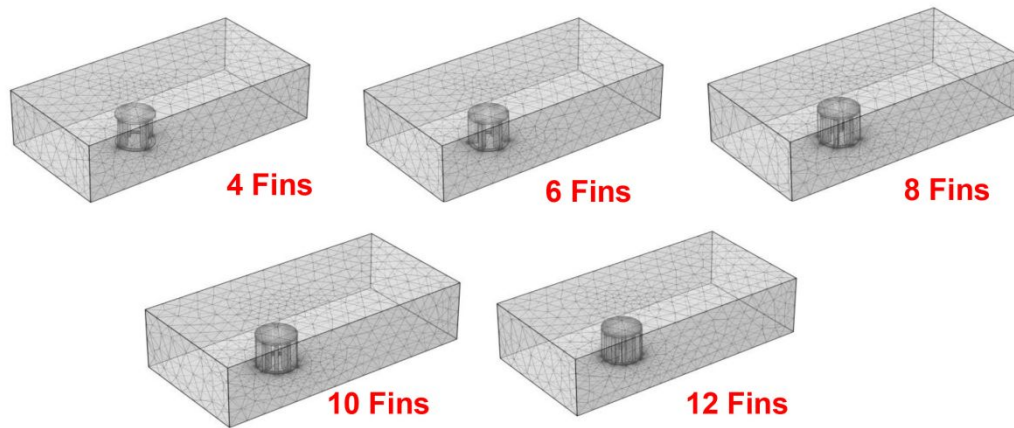


Figure S13. Air velocity and RH distribution simulation: (a) physical modeling and (b) mesh generation of five SGs.

16. Airflow distribution simulation across SGs

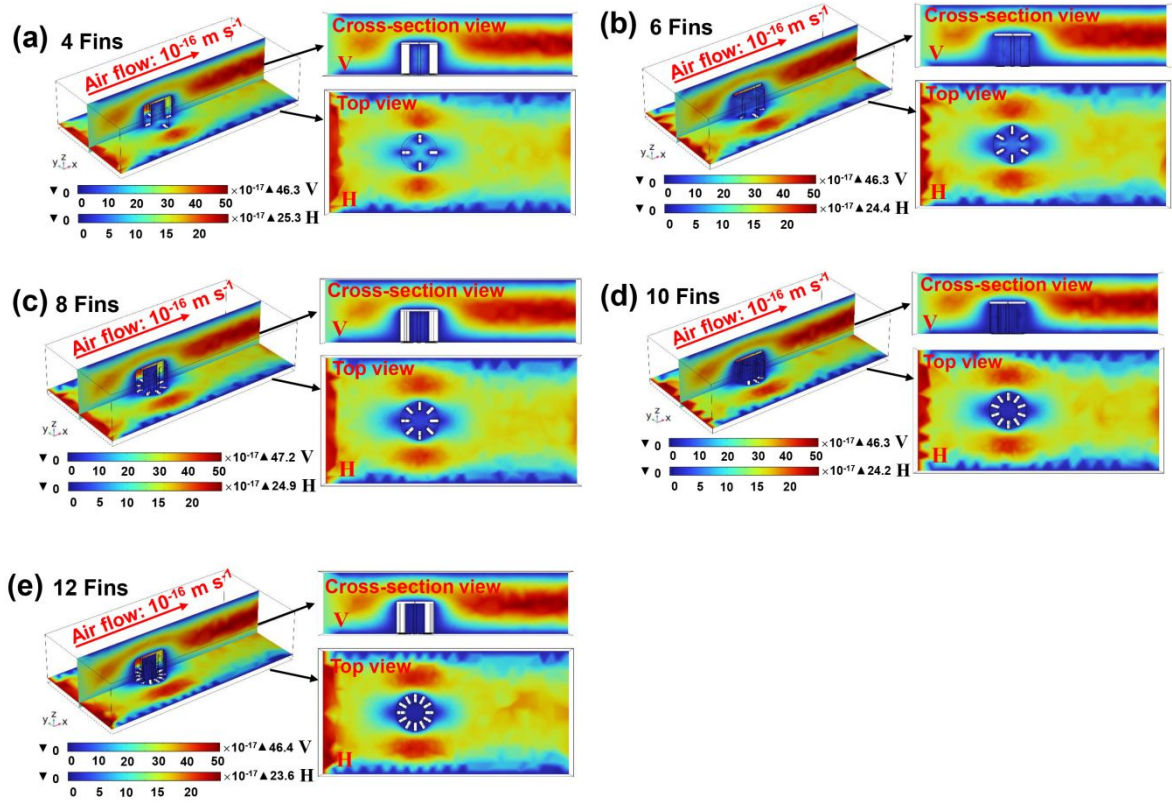


Figure S14. Airflow distributions across five SGs with varying fin number under calm (air velocity: $10^{-16} \text{ m s}^{-1}$) and 1 sun conditions: (a) 4 Fins, (b) 6 Fins, (c) 8 Fins, (d) 10 Fins and (e) 12 Fins.

17. RH distribution simulation across SGs

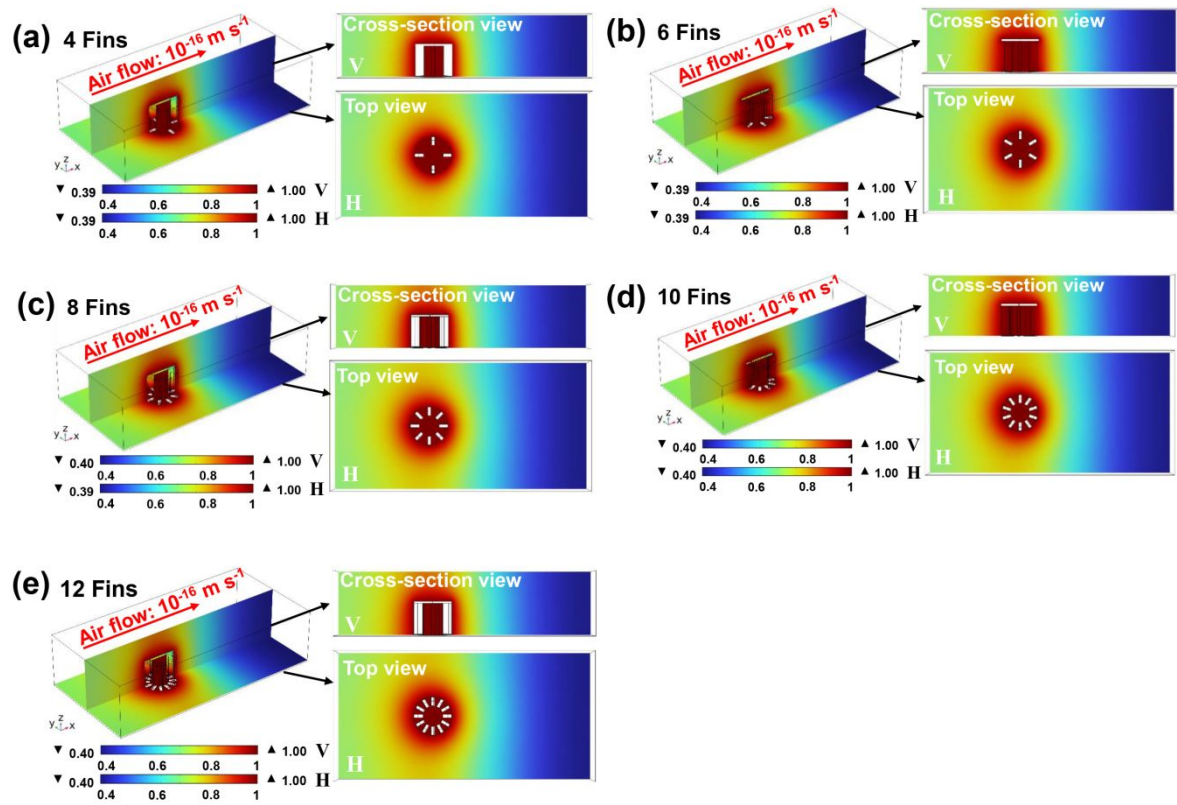


Figure S15. RH distributions across five SGs with varying fin number under calm (air velocity: $10^{-16} \text{ m s}^{-1}$) and 1 sun conditions: (a) 4 Fins, (b) 6 Fins, (c) 8 Fins, (d) 10 Fins and (e) 12 Fins.

18. Mesh generation of SG arrays

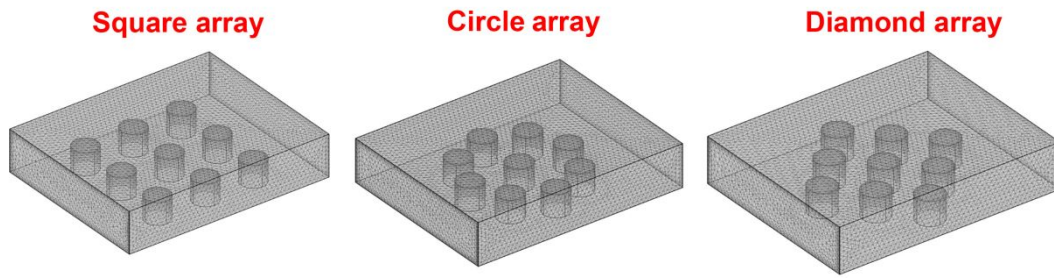


Figure S16. Particle distribution simulation mesh generation across square, circular and diamond arrays.

19. Process schematic of particle distribution simulation

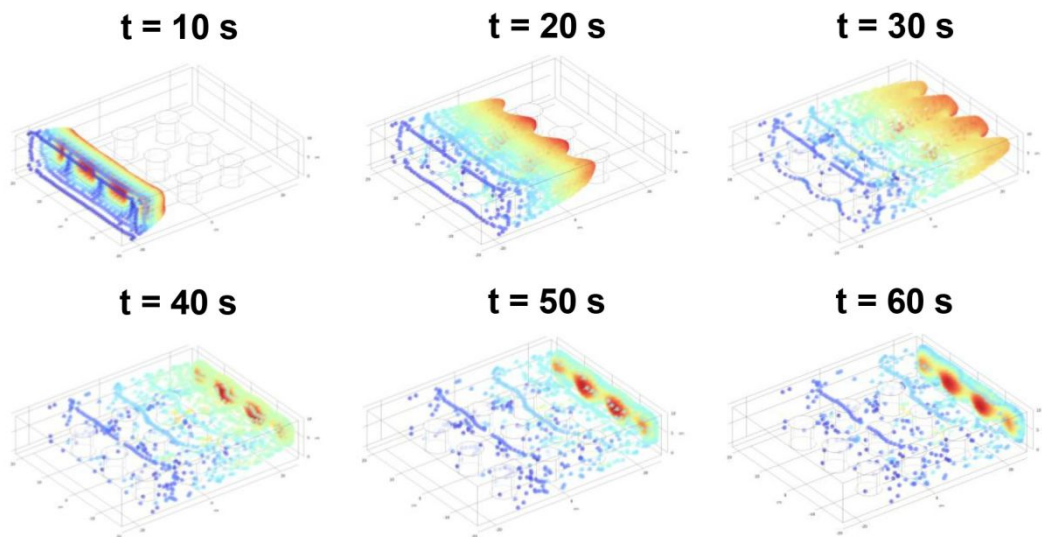


Figure S17. Particle distribution at $t = 10, 20, 30, 40, 50, 60$ for a convective velocity (air velocity: 0.01 m s^{-1}).

20. Air particle distribution simulation

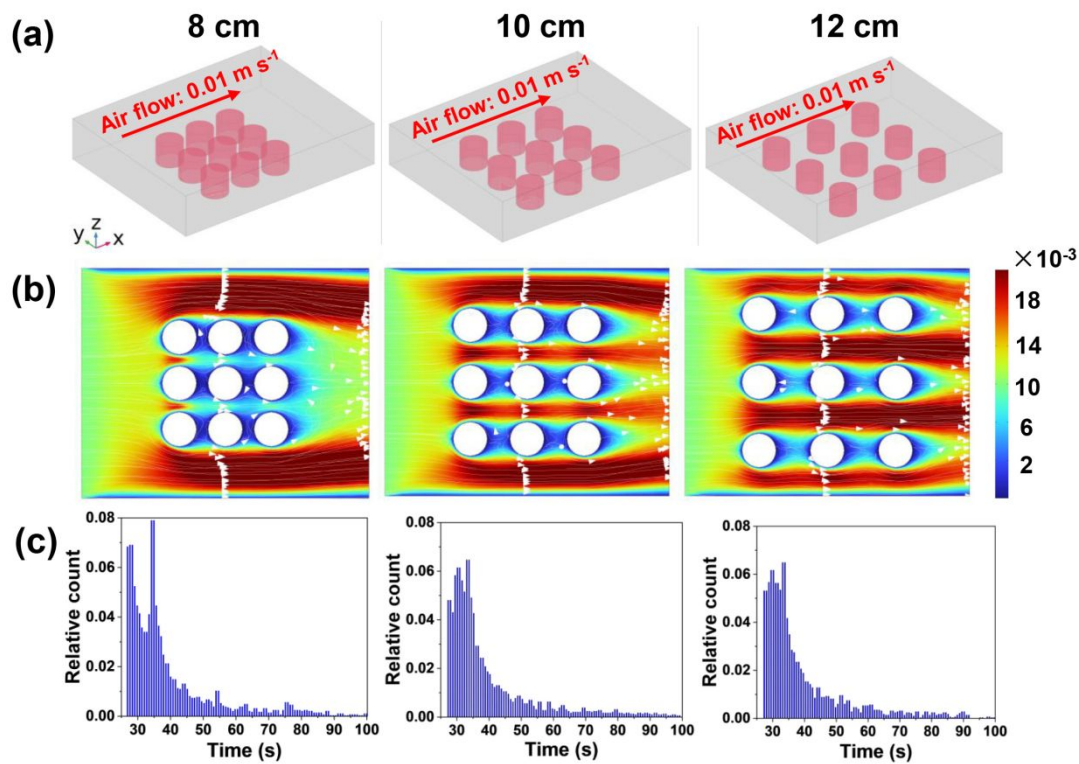


Figure S18. (a) Geometric modeling of square arrays (spacing distance: 8, 10 and 12 cm) based on 8-Fin SGs. Simulations of (b) air flow distribution and (c) dwell time distribution of air particles across square arrays under a light breeze (air velocity: 0.01 m s^{-1}).

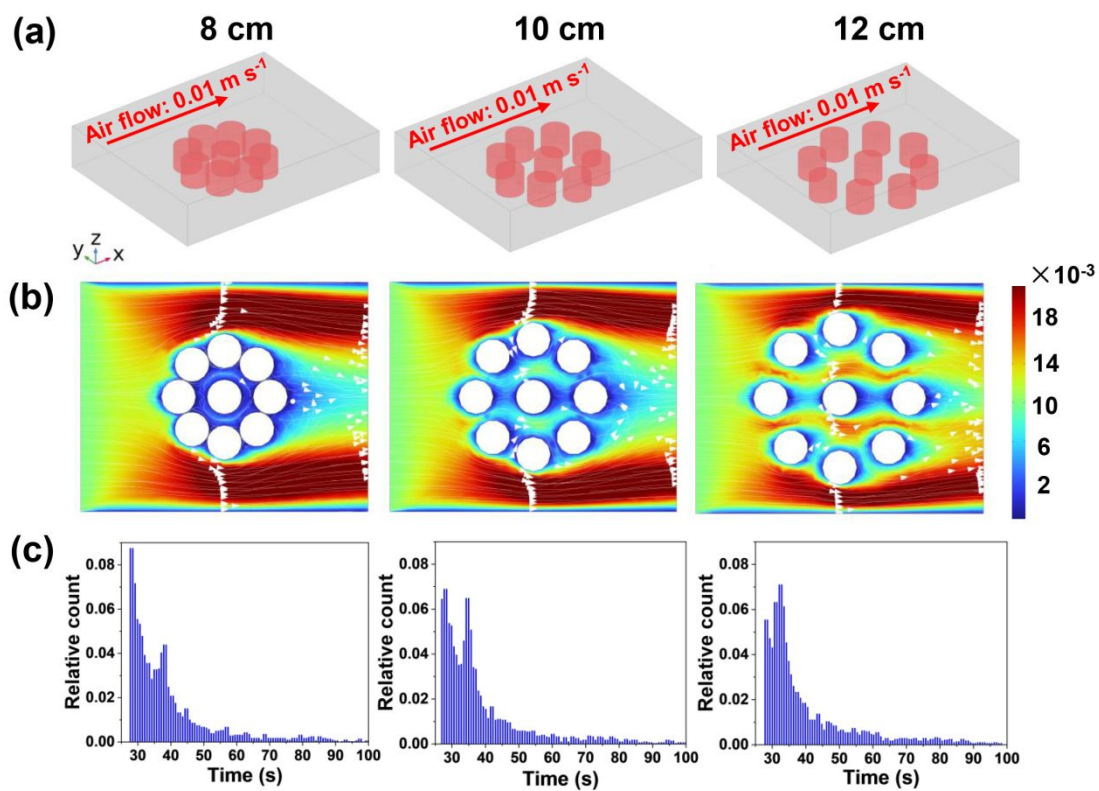


Figure S19. (a) Geometric modeling of circular arrays (spacing distance: 8, 10 and 12 cm) based on 8-Fin SGs. Simulations of (b) air flow distribution and (c) dwell time distribution of air particles across circular arrays under a light breeze (air velocity: 0.01 m s^{-1}).

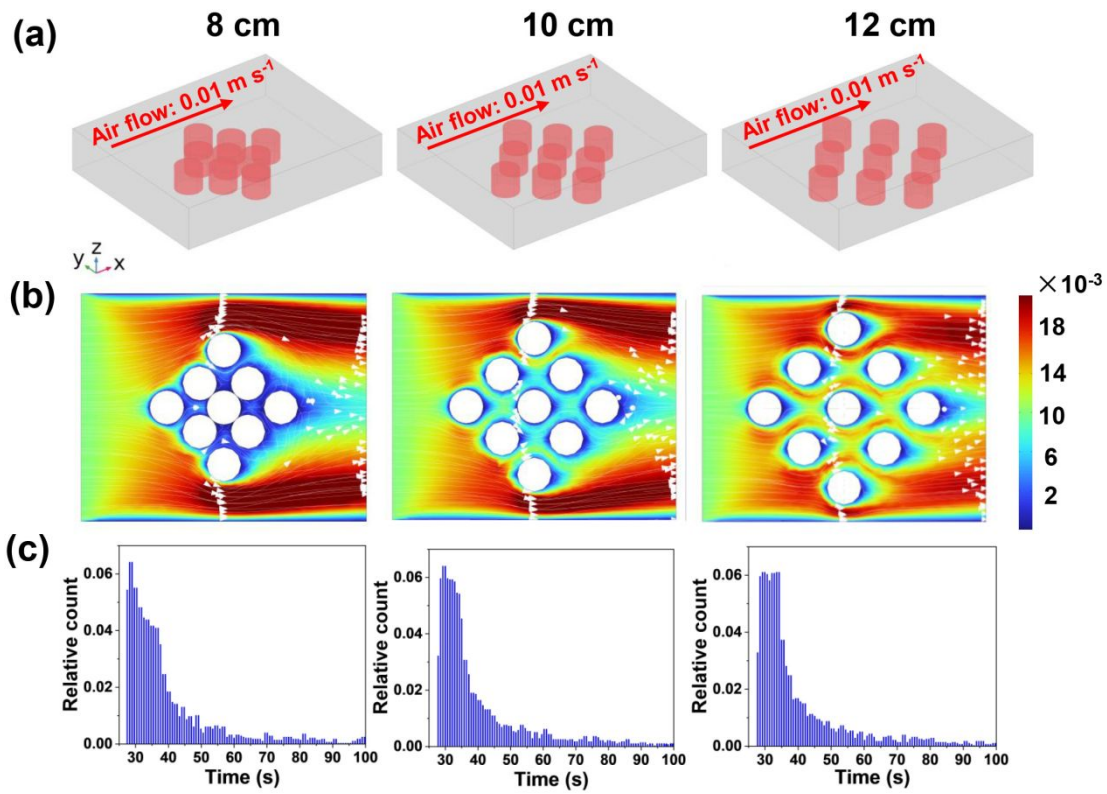


Figure S20. (a) Geometric modeling of diamond arrays (spacing distance: 8, 10 and 12 cm) based on 8-Fin SGs. Simulations of (b) air flow distribution and (c) dwell time distribution of air particles across diamond arrays under a light breeze (air velocity: 0.01 m s^{-1}).

21. Environment parameters under a real sky

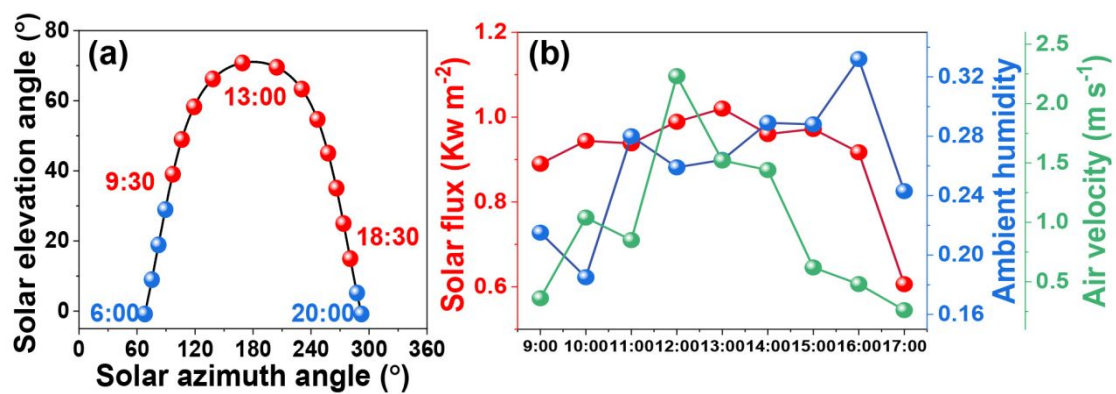


Figure S21. (a) The Sun's position on the sky dome. (b) Synchronous solar intensity, ambient humidity and air velocity at outdoor measurements.

22. Water evaporation characterization under real sky

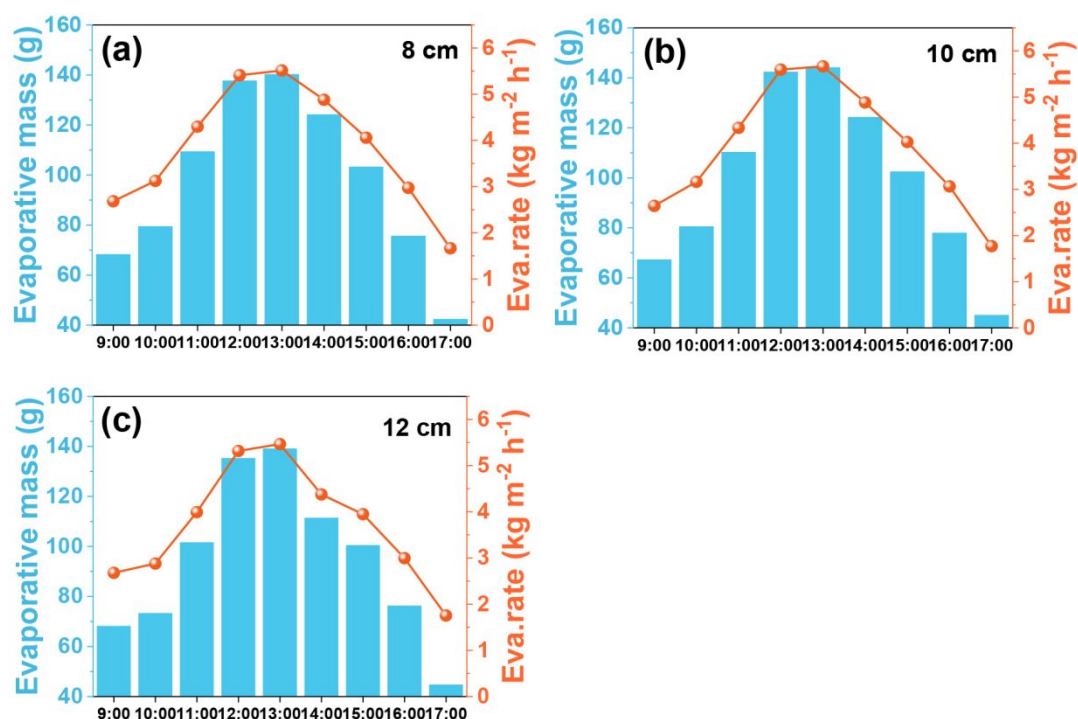


Figure S22. Water evaporation of square arrays with different spacing distance: (a) 8 cm, (b) 10 cm and (c) 12 cm.

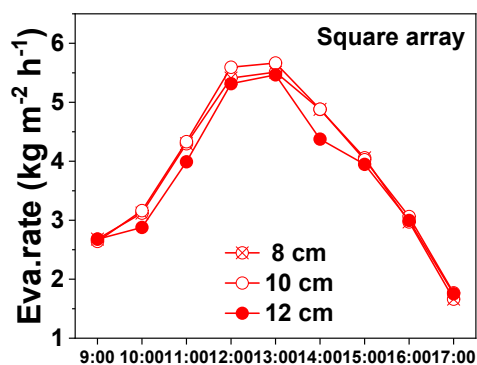


Figure S23. Summary of water evaporation rates of square arrays (spacing distance: 8, 10, 12 cm) in the daytime.

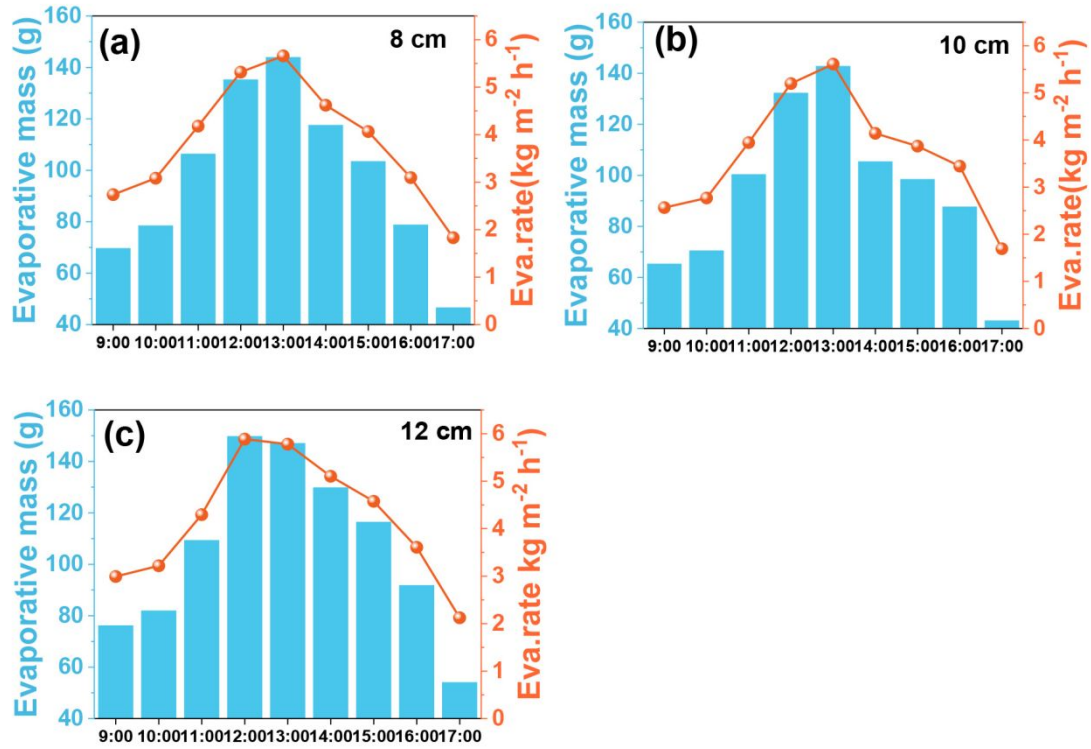


Figure S24. Water evaporation of circular arrays with different spacing distance: (a) 8 cm, (b) 10 cm and (c) 12 cm.

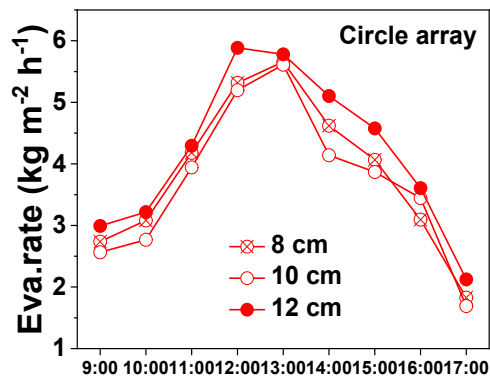


Figure S25. Summary of water evaporation rates of circular arrays (spacing distance: 8, 10 and 12 cm) in the daytime.

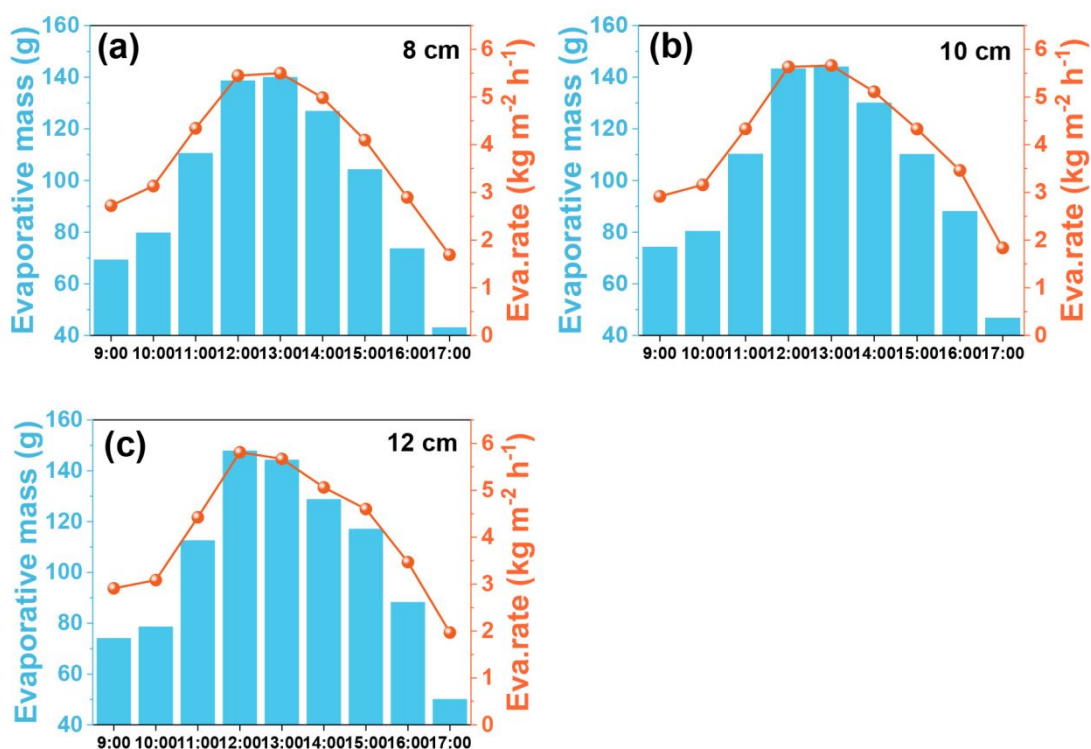


Figure S26. Water evaporation of diamond arrays with different spacing distance: (a) 8 cm, (b) 10 cm and (c) 12 cm.

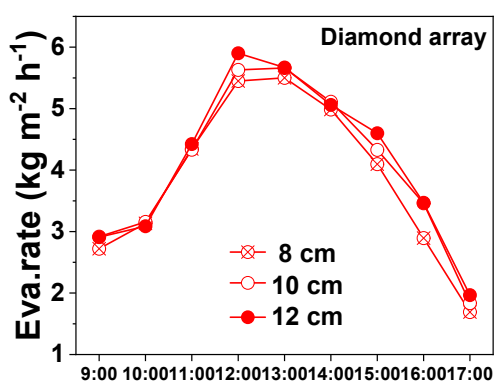


Figure S27. Summary of water evaporation rates of circular arrays (spacing distance: 8, 10 and 12 cm) in the daytime.

23. Outdoor evaporation of neat water

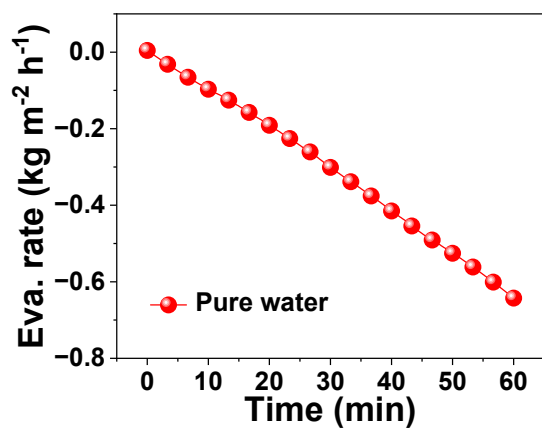


Figure S28. Evaporation of neat water under real sky at noon (12:00 – 13:00).

24. Outdoor clean water production

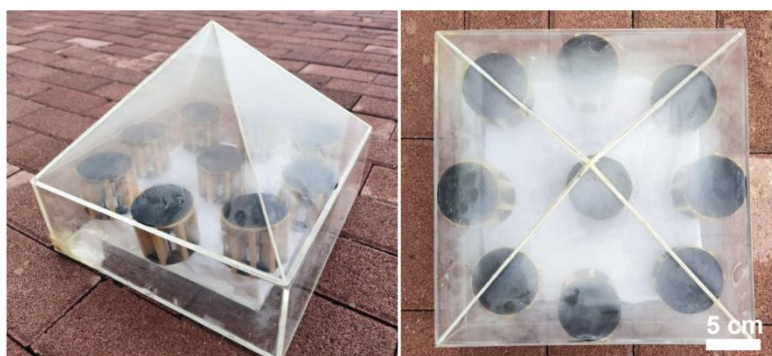


Figure S29. Digital photographs of clean water production device.

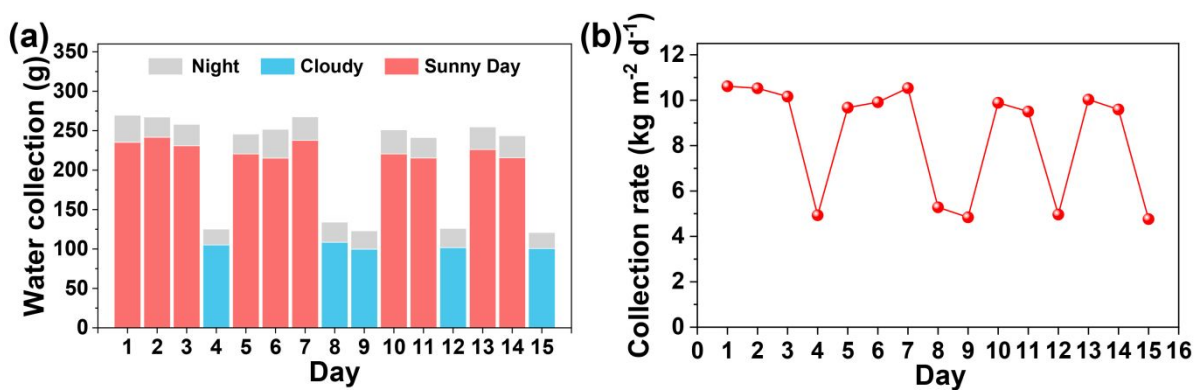


Figure S30. (a) Clean water yields and (b) rates of the device under real sky over 15 days.

25. Water quality characterization

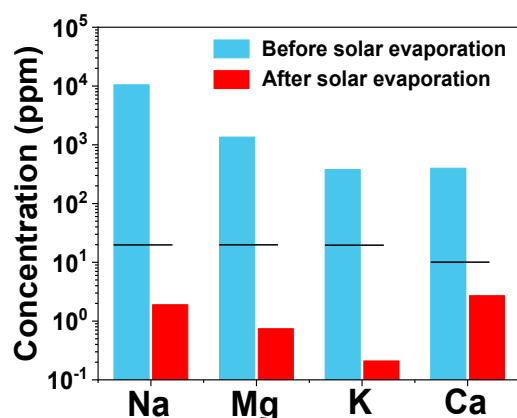


Figure S31. Concentrations of primary elements in water before and after solar evaporation. (The black lines indicate WHO quality standards for safe drinking water.)

26. Reference

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